



Summary

Shinichi nakajima (TU Berlin) <u>nakajima@tu-berlin.de</u> <u>http://sites.google.com/site/shinnkj23/</u>



Bayesian learning

Posterior:
$$p(\boldsymbol{w}|\mathcal{D}) = \frac{p(\mathcal{D}|\boldsymbol{w})p(\boldsymbol{w})}{p(\mathcal{D})}$$

where
$$p(\mathcal{D}) = \int p(\mathcal{D}|oldsymbol{w}) p(oldsymbol{w}) doldsymbol{w}$$

Analytically computed in the conjugate cases, e.g., Gaussian, Multinomial, etc.



Approximation methods

Conditionally conjugate

(Gaussian MF, Mixture of Gaussians, LDA)

Gibbs sampling

Variational Bayes

Non-conjugate (likelihood with sigmoid function)

Metropolis-Hastings

Local variational Bayes, Expectation Propagation



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Logistic regression

$$y \in \{-1, 1\},$$

 $oldsymbol{x} \in \mathbb{R}^{D},$
 $oldsymbol{w} \in \mathbb{R}^{D},$
 $\psi(z) = rac{1}{1 + e^{-z}}$



$$p(y|\boldsymbol{w}) = \psi(y\boldsymbol{w}^{\top}\boldsymbol{x})$$



Logistic regression

$$p(y|w) = \psi(yw^{\top}x)$$

$$= \frac{1}{1 + e^{-yw^{\top}x}}$$

$$= \frac{e^{\frac{yw^{\top}x}{2}}}{e^{\frac{yw^{\top}x}{2}} + e^{-\frac{yw^{\top}x}{2}}}$$

$$= \frac{e^{\frac{yw^{\top}x}{2}}}{e^{\frac{w^{\top}x}{2}} + e^{-\frac{w^{\top}x}{2}}}$$

$$\propto e^{\frac{yw^{\top}x}{2}}$$

$$egin{aligned} &y\in\{-1,1\},\ &oldsymbol{x}\in\mathbb{R}^D,\ &oldsymbol{w}\in\mathbb{R}^D,\ &oldsymbol{\psi}(z)=rac{1}{1+e^{-z}} \end{aligned}$$



 $y \in \{-1, 1\},\$

 $oldsymbol{x}\in\mathbb{R}^{D},$

 $\boldsymbol{w} \in \mathbb{R}^{D},$



Bayesian logistic regression

$$\begin{split} p(\boldsymbol{w}|\mathcal{D}) &\propto p(\mathcal{D}|\boldsymbol{w})p(\boldsymbol{w}) & y \in \{-1,1\}, \\ &= \prod_{n=1}^{N} \psi(y^{(n)}\boldsymbol{w}^{\top}\boldsymbol{x}^{(n)}) \exp\left(-\frac{\boldsymbol{w}^{\top}\boldsymbol{C}^{-1}\boldsymbol{w}}{2}\right) & \boldsymbol{x} \in \mathbb{R}^{D}, \\ & \boldsymbol{w} \in \mathbb{R}^{D}, \\ & \boldsymbol{w} \in \mathbb{R}^{D}, \\ & \boldsymbol{\psi}(z) = \frac{1}{1+e^{-z}} \end{split}$$

No conjugate prior





Bayesian logistic regression



$$egin{aligned} &y\in\{-1,1\},\ &oldsymbol{x}\in\mathbb{R}^D,\ &oldsymbol{w}\in\mathbb{R}^D,\ &oldsymbol{\psi}(z)=rac{1}{1+e^{-z}} \end{aligned}$$



Approximate with Gaussian







Bayesian logistic regression





Local variational approximation





Local variational approximation





Expectation propagation





Expectation propagation



 $\boldsymbol{\Theta} = \operatorname*{argmin}_{\boldsymbol{\Theta}} \operatorname{KL}(p(\boldsymbol{w}|\mathcal{D}) \| r(\boldsymbol{w};\boldsymbol{\Theta}))$

Exponential family: $r(\boldsymbol{w}|\boldsymbol{\eta}) = h(\boldsymbol{w})g(\boldsymbol{\eta}) \exp\left(\boldsymbol{\eta}^{\top}\boldsymbol{T}(\boldsymbol{w})\right)$

$$\frac{\partial}{\partial \boldsymbol{\eta}} \left\{ \langle \log p(\boldsymbol{w}|\mathcal{D}) \rangle_{p(\boldsymbol{w}|\mathcal{D})} - \langle \log r(\boldsymbol{w}|\boldsymbol{\eta}) \rangle_{p(\boldsymbol{w}|\mathcal{D})} \right\} = -\frac{\partial}{\partial \boldsymbol{\eta}} \log g(\boldsymbol{\eta}) - \langle \boldsymbol{T}(\boldsymbol{w}) \rangle_{p(\boldsymbol{w}|\mathcal{D})}$$
$$= \langle \boldsymbol{T}(\boldsymbol{w}) \rangle_{r(\boldsymbol{w}|\boldsymbol{\eta})} - \langle \boldsymbol{T}(\boldsymbol{w}) \rangle_{p(\boldsymbol{w}|\mathcal{D})}$$

Moment matching!

$$:: -\frac{\partial}{\partial \boldsymbol{\eta}} \log g(\boldsymbol{\eta}) = \frac{\partial}{\partial \boldsymbol{\eta}} \log \int h(\boldsymbol{w}) \exp\left(\boldsymbol{\eta}^{\top} \boldsymbol{T}(\boldsymbol{w})\right) d\boldsymbol{w}$$
$$= \frac{\int \boldsymbol{T}(\boldsymbol{w}) h(\boldsymbol{w}) \exp\left(\boldsymbol{\eta}^{\top} \boldsymbol{T}(\boldsymbol{w})\right) d\boldsymbol{w}}{\int h(\boldsymbol{w}) \exp\left(\boldsymbol{\eta}^{\top} \boldsymbol{T}(\boldsymbol{w})\right) d\boldsymbol{w}}$$
$$= \langle \boldsymbol{T}(\boldsymbol{w}) \rangle_{r(\boldsymbol{w}|\boldsymbol{\eta})}$$



Expectation propagation

$$T(w)\rangle_{r(w|\eta)} = \langle T(w)\rangle_{p(w|D)}$$
 Moment matching!

current distribution:
$$r(\boldsymbol{w}|\boldsymbol{\theta}) = p(\boldsymbol{w}) \prod_{n=1}^{N} \widetilde{r}(y^{(n)} \boldsymbol{w}^{\top} \boldsymbol{x}^{(n)} | \boldsymbol{\theta}^{(n)})$$

Step 1: $\widetilde{r}^{n}(\boldsymbol{w}) = \frac{\widetilde{r}(\boldsymbol{w})}{\widetilde{r}(\boldsymbol{w}|\boldsymbol{\theta}^{(n)})}$

Step 2:
$$\widetilde{r}(\boldsymbol{w}|\boldsymbol{\theta}^{(n)}) = \frac{1}{Z^{(n)}} \text{Gauss}(y^{(n)}\boldsymbol{w}^{\top}\boldsymbol{x}^{(n)}; \mu^{(n)}, \sigma^{2(n)})$$

where
$$Z^{(n)} = \int \widetilde{r}^{\backslash n}(\boldsymbol{w})\psi(y^{(n)}\boldsymbol{w}^{\top}\boldsymbol{x}^{(n)})d\boldsymbol{w},$$

$$\mu^{(n)} = \int y^{(n)}\boldsymbol{w}^{\top}\boldsymbol{x}^{(n)}\widetilde{r}^{\backslash n}(\boldsymbol{w})\psi(y^{(n)}\boldsymbol{w}^{\top}\boldsymbol{x}^{(n)})d\boldsymbol{w},$$

$$\sigma^{2(n)} = \int (y^{(n)}\boldsymbol{w}^{\top}\boldsymbol{x}^{(n)})^{2}\widetilde{r}^{\backslash n}(\boldsymbol{w})\psi(y^{(n)}\boldsymbol{w}^{\top}\boldsymbol{x}^{(n)})d\boldsymbol{w}.$$

1-D numerical integration is required in each iteration.



Bayesian learning

Pros:

Less prone to overfitting.

Information on uncertainty is available.

All unknowns (hyperparameters) can be estimated from observation through Bayesian model selection.

Cons:

Integral computation is required.







Clustering



Mixture models:

$$p(x) = \sum_{h=1}^{H} a_h \mathcal{N}(x; \mu_h, \sigma_h^2)$$

Maximum likelihood estimation results in



The plausible number of clusters is found.



H



The plausible rank (PCA-dimension) is found



Subspace clustering

Use *Y* for dictionary (i.e., D = Y):

$$Y = YX + \mathcal{E}$$

Estimate *X*, given *Y*:

$$\min_{X} \|Y - YX\|_{\mathrm{Fro}}^2 + \lambda \|X\|_{\mathrm{tr}}.$$

low-rankness inducing penalty







(a) 1R2RCT_B

(b) 2T3RCRT





(c) cars3

(d) cars10



Spectral clustering with affinity matrix $abs(X) + abs(X^{\top})$

gives clustering result.

Subspaces with plausible dimensionality is found.



Foreground/Background video separation

$$V = U^{\rm BG} + U^{\rm FG} + \mathcal{E}$$

Impose different types of sparsity on U^{BG} and U^{FG}





$$V = U^{\text{low-rank}} + U^{\text{element-wise}} + \mathcal{E}$$



FB/BG separation is made without manual tuning parameter.



Sparse estimation

 $\boldsymbol{\diamond} \ell_1$ regularization

$$L(x) = \|y - Ax\|^2 + \lambda \|x\|_1$$

Convex

 $ightarrow \lambda$ should be tuned.

Bayesian with automatic relevance determination

- non-convex (local solver, sparser solution)
- no hand-tuning parameters (including kernel parameters in GP)





Recent development

Metropolis Hastings is slow...

Hamiltonian Monte Carlo.

VB approximation can be crude...

Theoretical support.

Expectation propagation.

Slow in non-conjugate cases

Various variational methods (e.g., proximal gradient).

📌Big data

stochastic gradient.

distributed computation.

